



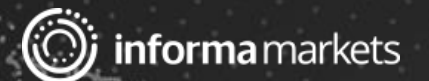
**DesignNews**

Expert C Techniques to Master Baremetal Programming

# DAY 2 : Building Cooperative Schedulers and Command Parsers

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- Participate in ‘Group Chat’ by maximizing the chat widget in your dock.

## THE SPEAKER



**Jacob Beningo**

Jacob@beningo.com

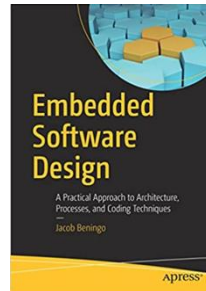


[jacobbeningo](#)

## Beningo Embedded Group – CEO / Founder

Focus: Software Architecture, Processes, and Dev Skills

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# •• Baremetal Scheduling

01

- No scheduler. No fancy operating system. Just a developer, a timer and the hardware.

# Baremetal Scheduling

## Round Robin Scheduling

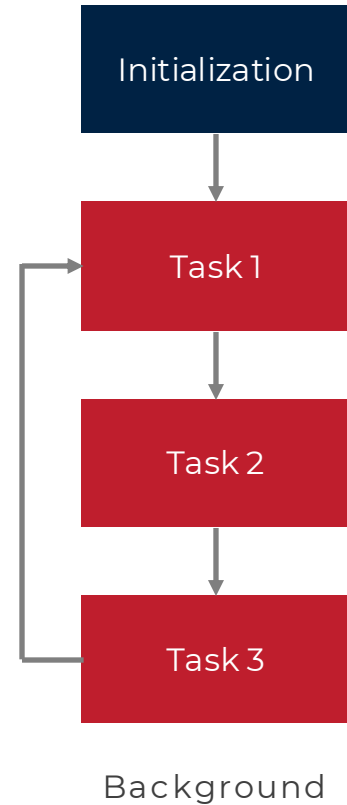
```
int main (void)
{
  System_Init();

  while(1)
  {
    // Run the first task
    Task1();

    // Run the first task
    Task2();

    // Run the first task
    Task3();
  }

  return 1;
}
```



# Baremetal Scheduling

## Round Robin Scheduling with Interrupts

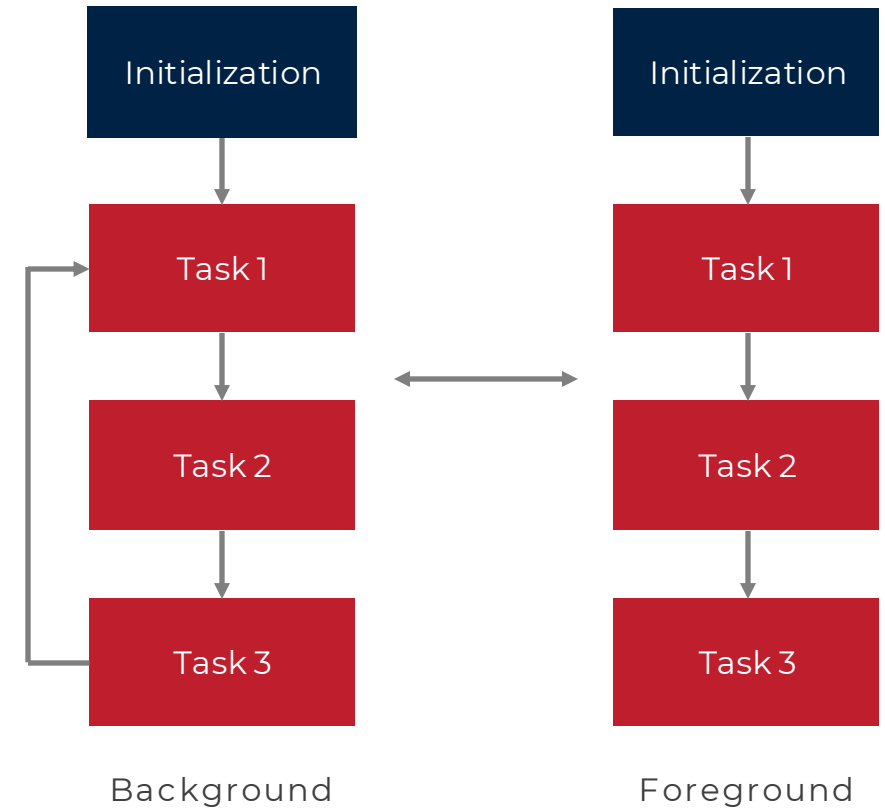
```
int main (void)
{
  System_Init();

  while(1)
  {
    // Run the first task
    Task1();

    // Run the first task
    Task2();

    // Run the first task
    Task3();
  }

  return 1;
}
```



## Audience POLL Question

What type of scheduler do you use?

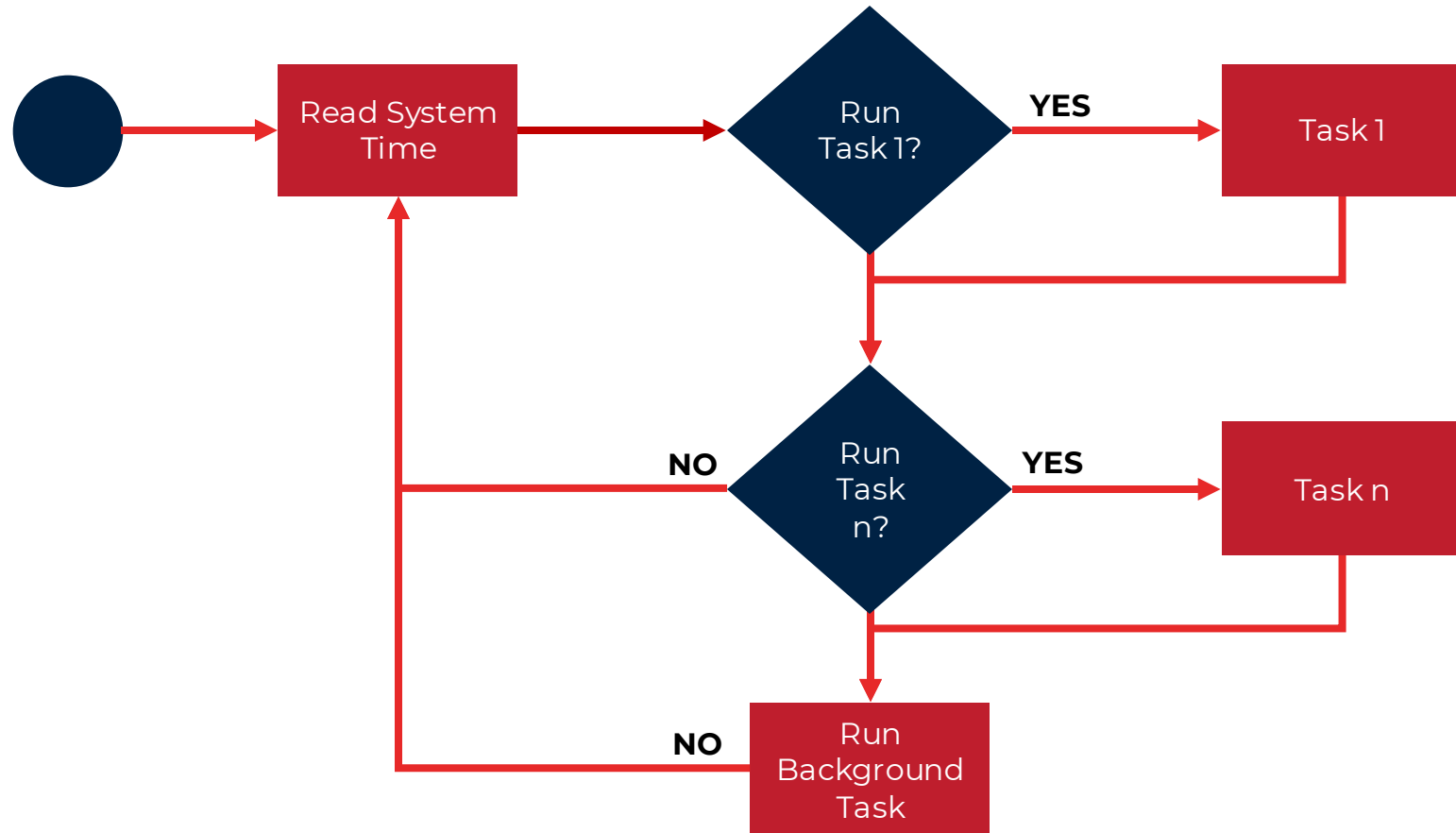
- a) Round Robin
- b) Round Robin with Interrupts
- c) Cooperative Scheduler
- d) RTOS
- e) Other

02

•• Designing a  
Cooperative Scheduler

# Designing a Cooperative Scheduler

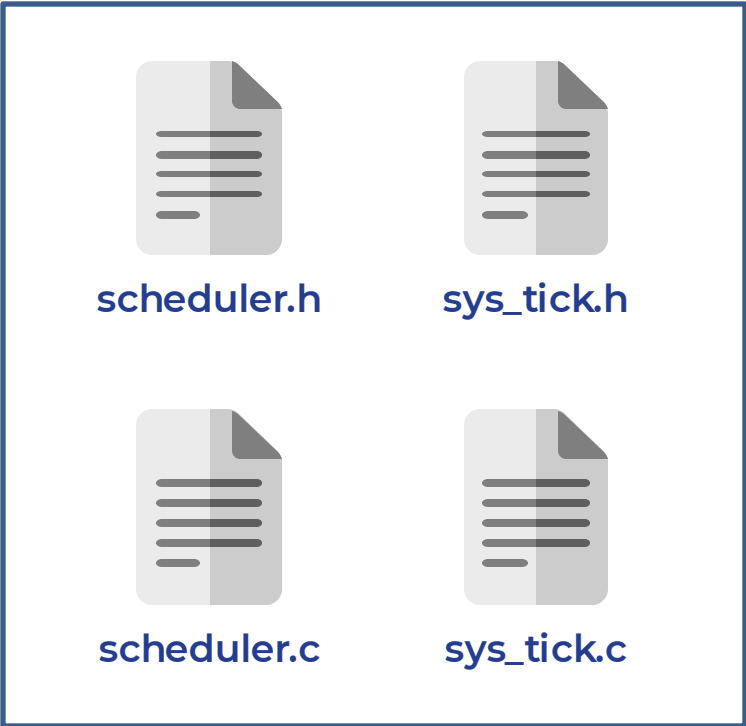
Design



# Designing a Cooperative Scheduler

## Organization

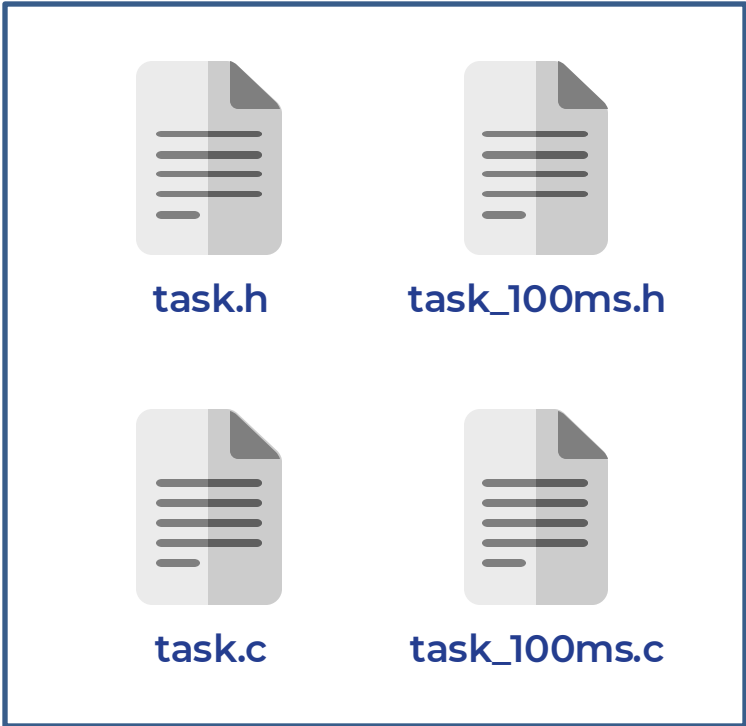
### “Operating System”



### Task Configuration



### Tasks



# Designing a Cooperative Scheduler

## Example Main

main.c

```
int main(void)
{
    // Initialize Peripherals and Application
    System_Initialize();

    // Initialize the scheduler
    OS_Init();

    for(;;)
    {
        OS_Run(HAL_GetTick);
    }

    return 0;
}
```

**Setup the scheduler** (points to OS\_Init)

**Run forever!** (points to for(;;))

**Timebase** (points to HAL\_GetTick)

**Cooperative scheduler** (points to OS\_Run)

task\_10ms.c

```
void Task_10ms()
{
    Led_Toggle(LED_GREEN);
}
```

task\_100ms.c

```
void Task_100ms()
{
    Led_Toggle(LED_RED);
}
```

task\_500ms.c

```
void Task_500ms()
{
    Led_Toggle(LED_BLUE);
}
```

# Designing a Cooperative Scheduler

## Creating Tasks

Separate  
Modules

```
#include "task.h"
void Task(void)
{
    // Code for background tasks
}
```

Task Code  
Placement

```
#include "task_10ms.h"
void Task_10ms(void)
{
    // Code for 10 ms task
}
```

## Audience POLL Question

How reusable do you think this scheduler is?

- a) Not at all
- b) Somewhat
- c) Very
- d) Other

03

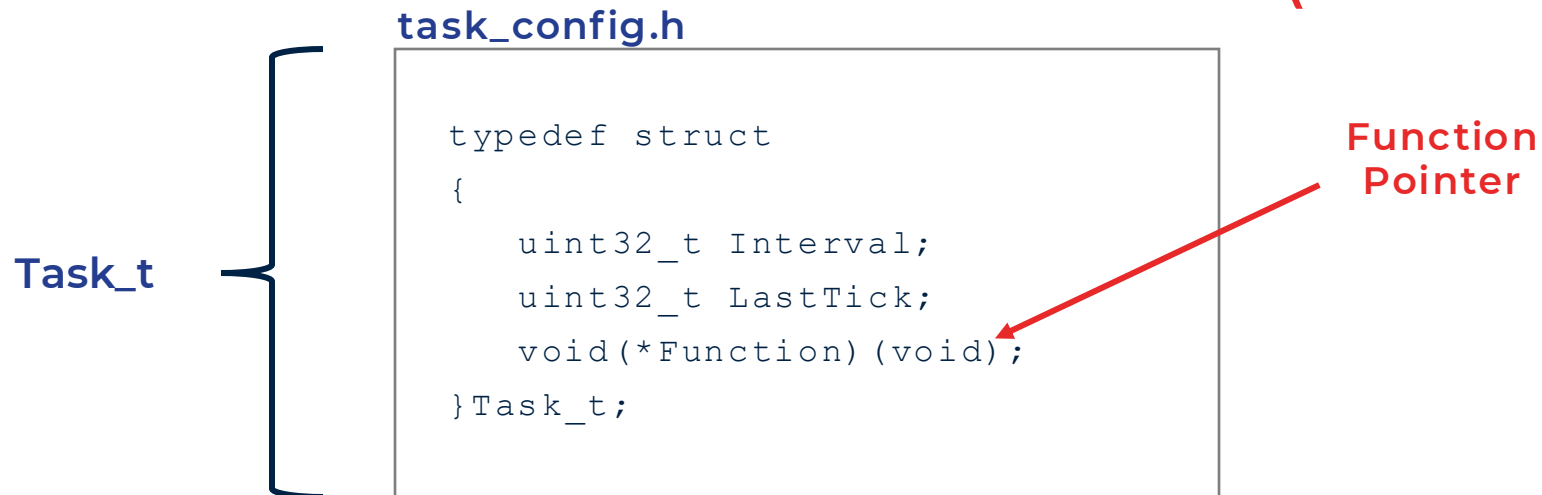
•• Cooperative Scheduler Implementation

# Cooperative Scheduler Implementation

## Task Management

What is the minimum amount of information required to schedule a periodic task?

- How often does the task need to run? **(Interval)**
- When did the task last run? **(LastTick)**
- What function should be called when it is time to run the task? **(Function)**



# Cooperative Scheduler Implementation

## Task Intervals

### task\_config.h

```
// Defines the rate at which the system tick is occurring in microseconds  
#define SYS_TICK_INTERVAL 1000UL
```

1000UL



Microseconds

### Background Interval

### Periodic Time Intervals

```
// Define the number of system ticks required for each interval  
#define INTERVAL_0MS 0  
#define INTERVAL_10MS (10000UL / SYS_TICK_INTERVAL)  
#define INTERVAL_50MS (50000UL / SYS_TICK_INTERVAL)  
#define INTERVAL_100MS (100000UL / SYS_TICK_INTERVAL)  
#define INTERVAL_500MS (500000UL / SYS_TICK_INTERVAL)  
#define INTERVAL_1000MS (1000000UL / SYS_TICK_INTERVAL)
```

# Cooperative Scheduler Implementation

OS\_Init

task\_config.c

```
Task_t Tasks[] =  
{  
  { INTERVAL_10MS , 0, Task_10ms      },  
  { INTERVAL_0MS  , 0, Task_Background }  
};
```

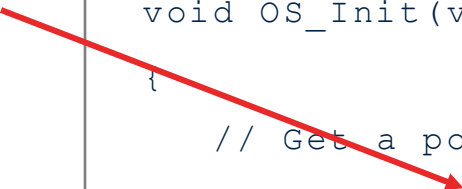
Tasks to run



scheduler.c

```
Task_t *Task_ptr = NULL;           // Points to a table of tasks  
  
void OS_Init(void)  
{  
  // Get a pointer to the task config  
  Task_ptr = Task_ConfigGet();  
}
```

Scheduler now  
knows where  
Tasks[] is!



# Cooperative Scheduler Implementation

## Task Configuration

Need to get the pointer to the Tasks table to the scheduler

### task\_config.c

```
Task_t *Task_ConfigGet(void)
{
    return Tasks;
}
```

How does the scheduler know how many tasks are in the table?

### task\_config.c

```
uint8_t Task_GetNumberOf(void)
{
    return sizeof(Tasks) / sizeof(*Tasks);
}
```

# Cooperative Scheduler Implementation

## OS\_Run

File scope variables used by the scheduler

```
static uint8_t  TaskIndex = 0;           // Task index
static uint32_t ElapsedInterval = 0;     // Time since last ran
```

```
void OS_Run(const uint32_t Tick)
{
    // Number of tasks
    const uint8_t NumberOfTasks = Task_GetNumberOf();

    /* Main Loop */
    ...
}
```

**Hardware Independent!**

# Cooperative Scheduler Implementation

## OS\_Run

```
/* Main Loop */

for(TaskIndex = 0; TaskIndex < NumberOfTasks; TaskIndex++)
{
    assert(TaskIndex < NumTasks);

    if((Tick - TaskPointer[TaskIndex].LastTick) >= TaskPointer[TaskIndex].Interval)
    {
        assert(TaskPointer[TaskIndex].Func != NULL;

        (*TaskPointer[TaskIndex].Function)();           // Execute Task
        Task_Pointer[TaskIndex].LastTick = Tick;       // Save tick the task was ran at.
    }
} // end for
```

## Audience POLL Question

What is the main mechanism used to execute a task?

- a) A function
- b) A function pointer
- c) A function pointer table
- d) None of the above

•• Next Steps

04

## Going Further

Download Function Pointer Example Code:

- Additional Video on Baremetal Scheduling
- Scheduling Lab Instructions
- Scheduler Source Code

<https://beningo.mykajabi.com/>



## Additional Resources

Please consider the resources below:

- [Jacob's Blogs](#)
- [Jacob's CEC courses](#)
- [Embedded Software Academy](#)
  
- Embedded Bytes Newsletter
  - <http://bit.ly/1BAHYXm>



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## Next Steps



Mastering Function Pointers for Baremetal Systems



Building Cooperative Schedulers and Command Parsers

Baremetal Performance Analysis and Architecture Design

Assertions and Validation Techniques for Baremetal

Managing Interrupts in Baremetal Systems



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